

دانشگاه آزاد اسلامی واحد تبریز



نام درس: طراحی و تحلیل الگوریتم های پیشرفته

بخش: الگوریتم های حریمانه

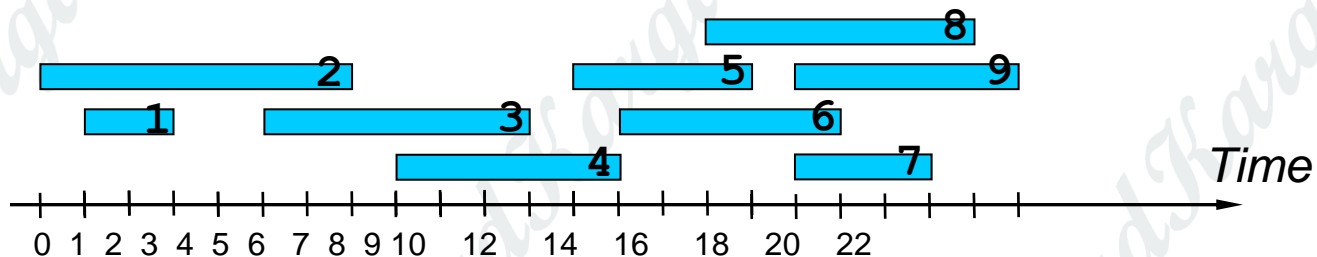
نام استاد: دکتر مسعود کارگر

Greedy Algorithms

- Goals of the lecture:
 - *to understand the **principles** of the greedy algorithm design technique;*
 - *to understand the **example greedy algorithms** for activity selection and Huffman coding, to be able to **prove** that these algorithms find optimal solutions;*
 - *to be able to **apply** the greedy algorithm design technique.*

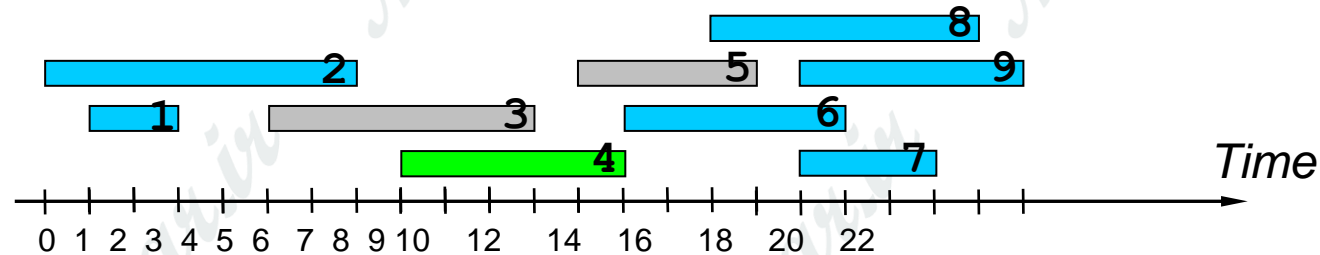
Activity-Selection Problem

- Input:
 - A set of n activities, each with start and end times: $A[i].s$ and $A[i].f$. The activity last during the period $[A[i].s, A[i].f)$
- Output:
 - The **largest** subset of mutually *compatible* activities
 - Activities are compatible if their intervals do not intersect



“Straight-forward” solution

- Let's just pick (schedule) one activity $A[k]$
 - This generates two set's of activities compatible with it: $Before(k)$, $After(k)$
 - E.g., $Before(4) = \{1, 2\}$; $After(4) = \{6, 7, 8, 9\}$



- Solution:

$$MaxN(A) = \begin{cases} 0 & \text{if } A = \emptyset, \\ \max_{1 \leq k \leq n} \{MaxN(Before(A)) + MaxN(After(A)) + 1\} & \text{if } A \neq \emptyset. \end{cases}$$

Dynamic Programming Alg.

- The recurrence results in a dynamic programming algorithm
 - Sort activities on the start or end time (for simplicity assume also “sentinel” activities $A[0]$ and $A[n+1]$)
 - Let S_{ij} – a set of activities after $A[i]$ and before $A[j]$ and compatible with $A[i]$ and $A[j]$.
 - Let’s have a two-dimensional array, s.t., $c[i, j] = \text{MaxN}(S_{ij})$.

$$c[i, j] = \begin{cases} 0 & \text{if } S_{ij} = \emptyset, \\ \max_{i < k < j} \{c[i, k] + c[k, j] + 1\} & \text{if } S_{ij} \neq \emptyset. \end{cases}$$

- $\text{MaxN}(A) = \text{MaxN}(S_{0, n+1}) = c[0, n+1]$

Dynamic Programming Alg. II

- Does it really work correctly?
 - We have to prove the optimal sub-structure:
 - *If an optimal solution A to S_{ij} includes $A[k]$, then solutions to S_{ik} and S_{kj} (as parts of A) must be optimal as well*
 - To prove use “cut-and-paste” argument
- What is the running time of this algorithm?

Greedy choice

- What if we could choose “the best” activity (as of now) and be sure that it belongs to an optimal solution
 - We wouldn't have to check out all these sub-problems and consider all currently possible choices!
- Idea: Choose the activity that finishes first!
 - Then, solve the problem for the remaining compatible activities

MaxN(A[1..n], i) //returns a set of activities

```
01 m ← i + 1
02 while m ≤ n and A[m].s < A[i].f do
03     m ← m + 1
04 if m ≤ n then return {A[m]} ∪ MaxN(A, m)
05     else return ∅
```

Greedy-choice property

- What is the running time of this algorithm?
- Does it find an optimal solution?:
 - We have to prove the *greedy-choice property*, i.e., that our locally optimal choice belongs to some globally optimal solution.
 - We have to prove the *optimal sub-structure* property (we did that already)
- The challenge is to choose the right interpretation of “the best choice”:
 - How about the activity that starts first
 - Show a *counter-example*

Data Compression

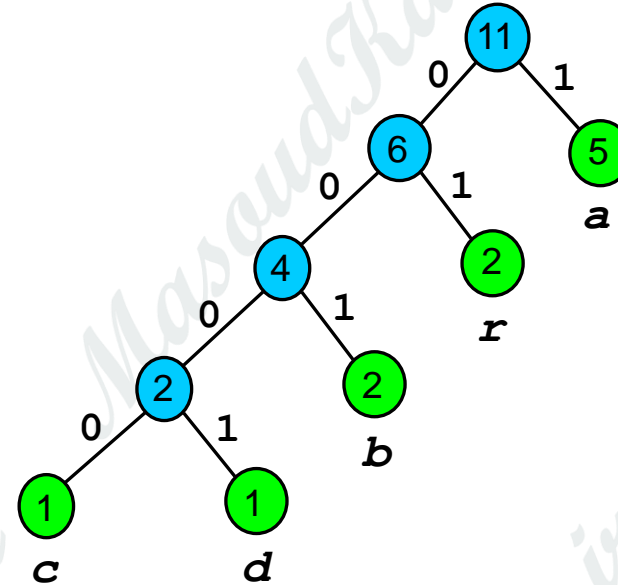
- *Data compression* problem – strings S and S' :
 - $S \rightarrow S' \rightarrow S$, such that $|S'| < |S|$
- Text compression by coding with *variable-length* code:
 - Obvious idea – assign short codes to frequent characters:
“**abracadabra**”
 - Frequency table:

	a	b	c	d	r
Frequency	5	2	1	1	2
Fixed-length code	000	001	010	011	100
Variable-length code	1	001	0000	0001	01

- How much do we save in this case?

Prefix code

- Optimal code for given frequencies:
 - Achieves the minimal length of the coded text
- **Prefix code**: no codeword is prefix of another
 - It can be shown that optimal coding can be done with prefix code



- We can store all codewords in a **binary trie** – very easy to decode
 - Coded characters in leaves
 - Each node contains the sum of the frequencies of all descendants

Optimal Code/Trie

- The cost of the coding trie T :

$$B(T) = \sum_{c \in C} f(c) d_T(c)$$

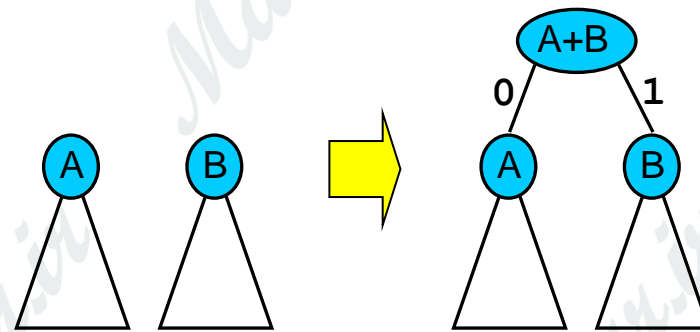
- C – the alphabet,
 - $f(c)$ – frequency of character c ,
 - $d_T(c)$ – depth of c in the trie (length of code in bits)
- Optimal trie – the one that minimizes $B(T)$
 - Observation – optimal trie is always full:
 - Every non-leaf node has two children. Why?

Huffman Algorithm - Idea

- Huffman algorithm, builds the code trie bottom up.

Consider a forest of trees:

- Initially – one separate node for each character.
- In each step – join two trees into a larger tree



- Repeat this until one tree (trie) remains.
- Which trees to join? Greedy choice – the trees with the **smallest** frequencies!

Huffman Algorithm

Huffman (C)

```
01 Q.build(C) // Builds a min-priority queue on frequencies
02 for i ← 1 to n-1 do
03     Allocate new node z
04     x ← Q.extractMin()
05     y ← Q.extractMin()
06     z.setLeft(x)
07     z.setRight(y)
08     z.setF(x.f() + y.f())
09     Q.insert(z)
10 return Q.extractMin() // Return the root of the trie
```

- What is its running time?
- Run the algorithm on: “oho ho, ole”

Correctness of Huffman

- Greedy choice property:
 - Let x, y – two characters with lowest frequencies. Then there exists an optimal prefix code where codewords for x and y have the same length and differ only in the last bit
 - Let's prove it:
 - Transform an optimal trie T into one (T''), where x and y are max-depth siblings. Compare the costs.

Correctness of Huffman

- Optimal sub-structure property:
 - Let x, y – characters with minimum frequency
 - $C' = C - \{x, y\} \cup \{z\}$, such that $f(z) = f(x) + f(y)$
 - Let T' be an optimal code trie for C'
 - Replace leaf z in T' with internal node with two children x and y
 - The result tree T is an optimal code trie for C
- Proof a little bit more involved than a simple “cut-and-paste” argument

Elements of Greedy Algorithms

- Greedy algorithms are used for optimization problems
 - A number of choices have to be made to arrive at an optimal solution
 - At each step, make the “locally best” choice, without considering all possible choices and solutions to sub-problems induced by these choices (compare to dynamic programming)
 - After the choice, only one sub-problem remains (smaller than the original)
- Greedy algorithms usually sort or use priority queues

Elements of Greedy Algorithms

- First, one has to prove the *optimal sub-structure* property
 - the simple “cut-and-paste” argument may work
- The main challenge is to decide the interpretation of “the best” so that it leads to a global optimal solution, i.e., you can prove the *greedy choice property*
 - The proof is usually constructive: takes a hypothetical optimal solution without the specific greedy choice and transforms into one that has this greedy choice.
 - Or you find counter-examples demonstrating that your greedy choice does not lead to a global optimal solution.

Other Greedy Algorithms

- Find a minimum spanning tree in a weighted graph
- Coin changing